DIY Antenna Amplification and Automated Aiming Systems Marty Rand, Dane Schoelen Norman Advanced Robotics yagimoto.martionlabs@gmail.com, daneschoelen@gmail.com

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1. Introduction

At the 2011 Global Conference on Educational Robotics, Internet was unavailable in the main ballroom. While it was possible to buy Internet for hotel rooms, it seemed impossible to get that Internet in the ballroom. A Rosewill RNX-N180UBE (source: rosewill.com [1]) wifi card with -78 dBm sensitivity and a 5 dBi omnidirectional antenna was unable to reliably connect to the hotel's wifi. -78 dBm was inadequate for such a long-range connection, and a 5 dBi omnidirectional antenna did not offer enough gain. A more sensitive wifi card coupled with a more powerful directional antenna would have helped establish a better signal. Even with a directional antenna, aiming it precisely at the access point is tricky. A robot that automatically aims the antenna would help immensely. This also applies to office and home environments where the access point is out of reach of a user's computer. Many offices do not approve of employees setting up personal routers, but they would allow larger antennas. In this paper, we discuss terminology, wifi cards, antennas, and an antenna-aiming robot, Project Yagimoto.

2. Terminology

2.1 dBi

source: wikipedia.org [2]

dBi is a measure of wifi antenna gain, or in this case, size. The larger the antenna, the more dBi it has. Larger antennas can detect wifi networks further away from the user, but have less room for error (see Antenna Tilting). The formula for dBi is $Gain = 10 * \log(\frac{linear intensity}{isotrop ic intensity})$. Linear intensity is power along one axis, whereas isotropic intensity is power extending outward in a sphere from a central point. A 0 dBi antenna has a spherical (isotropic) area of effect.

2.2. dBm

source: wikipedia.org [3]

dBm is a measure of power compared to 1 milliwatt. The formula for dBm is: $dBm = 10 * \log P + 30$ where P is the ratio of power (in milliwatts) compared to 1 milliwatt. 0 dBm is 1 milliwatt. 30 dBm is 1000 milliwatts, or 1 watt.

2.3 Reception Sensitivity

source: wikipedia.org [3]

Sensitivity, measured in dBm, is the weakest signal the wifi card can detect. This is crucial for establishing a stable connection at long distances. Furthermore, sensitivity is the most important thing to look for when wifi card shopping. Sensitivity is usually different at different data rates. For example, 802.11b, with a data rate of 11 Mbit/s, has better sensitivity than 802.11g, with a data rate of 54 Mbit/s. In addition, within 802.11g there are different data rates with different

sensitivity ratings. In general, the slower the connection, the greater the sensitivity is. All of the sensitivity ratings in this paper are for 802.11g at 54 Mbit/s. Sensitivity values for wifi cards are negative. Most wifi cards have a sensitivity rating in the -70 dBm to -95 dBm range. When converted into watts, sensitivity ratings range from 100 picowatts (pW) to ~.3 pW, meaning for every 10 dBm lower the sensitivity is it takes 1/10th the signal of achieve a connection. In other words, the lower (more negative) the sensitivity, the better the connection will be.

2.4 Transmission Power

source: wikipedia.org [3]

Transmission power, also measured in dBm, is the power applied to the antenna. Transmission power for most wifi cards ranges from 15 dBm to 32 dBm. Converted into watts, that equates to .03 W - 1.58W. The main limiting factor of transmission power is the 5-watt power limit of USB. Many manufacturers have circumvented this by having a USB Y cable that connects two USB ports to one wifi card, allowing for much greater transmission power and range.

Name	Source	Sensitivity (dBm) (pW)	Transmission Power (dBm) (W)	Bundled Antenna Size (dBi)	Comments
Intel WiFi Link 5100 AGN	intel.com [4]	Unknown	Unknown	Internal Only	awful sensitivity, very poor gain, Dell Studio XPS 1640's built-in wifi card, control
Rosewill RNX- N180UBE	rosewill.com [1]	-78 (15.8)	17 (.05)	5	smallest form factor of the wifi cards tested that accept external antennas
Rosewill RNX- N250UBE	rosewill.com [5]	-89 (1.3)	18 (.06)	2x5	sequel Rosewill RNX-N180UBE, 2 RP-SMA antenna inputs
Rosewill RNX- N2LX	rosewill.com [6]	-92 (.63)	17 (.05)	2x2	big brother of the RNX-N250UBE, ties for best sensitivity, 2 RP-SMA antenna inputs, newest and largest of Rosewill's wifi cards
Alfa AWUS036H	alfa.com.tw [7]	-71 (79.4)	24 (.25)	5	excellent Linux compatibility, advertises itself for extreme long rage communication
EnGenius EUB9603H	engeniustech .com [8]	-85 (3.2)	20 (.1)	5	has balance trouble with large antennas because the RP-SMA jack is off center, a weight fixed this
EDIMAX EW- 7811Un	edimax.com [9]	-71 (79.4)	15 (.03)	Internal Only	~5mm long, smallest wifi card tested, great for connecting to two different strong wifi networks, chosen to compare with larger cards that accept external antennas
Alfa AWUS036NHR	alfa.com.tw [10]	-92 (.63)	32 (1.58)	5	ties for best sensitivity, very new chipset

3. Wifi Cards Tested

4. Wifi Card Drivers

The built-in wifi card drivers that come with Windows are often old and outdated. With an EnGenius EUB9603H, we saw nearly twice as many wifi networks after we updated the drivers to the latest from the manufacturer's website. All tests listed in this paper use the newest drivers available.

5. Omnidirectional Antennas

Omnidirectional Antennas are the most common type of antenna. As their name implies, these antennas can see wifi networks in a 360-degree area around the antenna. Omnidirectional

Antennas are the most convenient antenna type because little to no aiming is involved. However, to achieve maximum signal quality, you may need to tilt the antenna (see Omnidirectional Antenna Size Selection).

6. Omnidirectional Antenna Size Selection

As an omnidirectional antenna increases in size, the range perpendicular to the antenna increases, but the range parallel to the antenna decreases. If you want to access a wifi network down the street, the larger the antenna the better. At the same time, the bigger the antenna, the less tolerance for the antenna tilting. Going larger than 5 dBi makes it very difficult to properly aim the antenna. If you want to access wifi networks ten stories higher than the antenna, a large antenna placed horizontally would be best. If you want to have a portable yet powerful antenna, a 5 dBi omnidirectional antenna would be ideal (from our testing).

7. Directional Antennas

A directional antenna has far better range than an omnidirectional antenna, but only functions in one direction. While there are many types of directional antennas, this paper addresses parabolic reflectors, cantennas, and yagis. In the case of directional antennas, the greater the dBi, the better the range, and the more directional the antenna is. That means that a 25 dBi directional antenna will reach very far away, but will be very precise, and will require exact aiming to get any signal at all. By the same logic, a 16 dBi directional antenna requires less precise aiming, but cannot connect to wifi networks as far away as a 25 dBi directional.



8. Antenna Tilting

As stated above, the larger an omnidirectional antenna gets, the further it can reach perpendicular to the antenna, but the less it can see parallel to the antenna. This means that if a large omnidirectional antenna tilts, it will have a significant range loss. This happens because the antenna's area of effect covers the underground or the sky rather than the lobby of the hotel. This issue also occurs with directional antennas. The more powerful a directional antenna, the narrower the area of effect is and the more precise the required aiming is.

9. EZ-12 "Windsurfer" Parabolic Reflector

Source: freeantennas.com [11]

This wifi range extender is, by far, the easiest and cheapest, as the materials include aluminum foil, a file folder, and adhesive. The construction of this Parabolic Reflector is very straightforward. Simply print and cut out the template, glue aluminum foil and the template to a

file folder, put the tabs in the slots, and place the resulting metallic paraboloid around any vertical antenna. The maker states that the normal size adds about 9 dBi of gain to an antenna. The normal size is only enough to fit around a 2 dBi antenna. Simply enlarge the image until the template size matches the antenna size that is being used. Alternatively, print out multiple copies of the normal size and stack them on the antenna. This method will not achieve as much gain unless a small piece of aluminum foil is placed over the gap between the different reflectors.

10. Directional Cantennas: from Steel Cans

This was the first kind of homemade antenna modification we attempted. The cantenna is the stereotypical homemade antenna mod. All this mod does is place an omnidirectional antenna inside a metal can to reflect the radio waves out the can in one direction. This is a very simple modification. All that is necessary is to drill a hole in the side of the can and put the antenna into it. However, we wanted better results. We glued a Windsurfer (discussed above) to the back of the can and lined up the hole in the can with the hole in the Windsurfer. This makes a perfect paraboloid for the antenna, allowing the radio waves to reflect out the antenna with less hindrance, and more accuracy. For this mod to work ideally, the selected can should have a diameter equal to the length of the inserted antenna. The depth of the can determines the precision of the antenna. The taller the can, the further it can reach, but the less room for error you have. The bigger the diameter of the can, the further it can reach. This is because the antenna will send the radio waves in a more direct route to the access point.

11. Directional Cantennas: from Dryer Tubing

Cans only come so big. If you want a 7 in diameter can, you are out of luck. Although, they make dryer tubing much larger than that. A 7 in tube is the right size for a 5 dBi antenna. Dryer tubing does not come with a cap on one end, so we made our own by duct taping several layers of aluminum foil to one end. We then did the same procedure as we did with a real can.

12. Directional Yagi Antennas

Yagi antennas are the most linear directional antennas of the ones tested. These antennas are best known for their use as roof-mounted TV antennas. They look like giant metal fish bones. These antennas are very useful for aiming because it is easy to see where they are pointing. These antennas are also very easy to mount to a robot because they often come with metal plates that can screw onto almost anything.

13. Tripods

A small tabletop tripod is useful for aiming high powered directional antennas, because of the minimal room for error. We used a Vanguard VS-82 tabletop tripod (source: vanguardworld.com [12]) for aiming all of our directional antennas to achieve the maximum signal strength.

14. Tripod Mounts

Most tripods come with a screw (size may vary) that is designed to go into the bottom of a camera. You can attach an aluminum plate to most tripods by drilling a hole in the plate slightly larger than the screw. The yagi antennas we tested come with a metal plate perfect for this. For the cantennas, you can attach a piece of PVC pipe to the metal plate using U brackets, with which the yagi antennas also come.

15. Obstructions

One of the biggest factors effecting signal strength is the number and size of the objects in the antenna's path. Metal reflects radio waves, and most buildings have a considerable amount of metal. Furthermore, all non-metal objects impede radio waves. They just might not reflect all of the waves. This is why a connection in the middle of a prairie will go much farther than in a city.

16. Finding Wifi Networks

Obviously, it is impossible to aim a directional antenna if the location of the access point is unknown. A good way to localize an access point is to use a wardriving app for a smart phone. These apps will log nearby wifi networks, along with the GPS location of the phone. We recommend Wigle Wifi Wardriving for Android (source: play.google.com [13]). With this, all you would do is walk around the area with the app running, and then look at the map it generated. Then, aim the directional antenna at the approximate location where the phone received the best signal strength. We used this technique in the included tests to locate nearby network candidates.

17. Wifi Networks Used for Testing

For the purposes of these tests, we chose the wifi networks based on distance from the antenna, and the number of obstructions between the antenna and the access point. The networks, with their names redacted, are as follows.

- 1. A local wifi network (similar to a standard home setup)
- 2. A wifi network 10ft away, but through a metal obstruction, without an alternate path. We did this by wrapping aluminum foil around each antenna.
- 3. A wifi network 1 house away
- 4. A wifi network ~400ft away, and through ~3 houses
- 5. A wifi network ~400ft away, and through ~6 houses

18. Test Result Summary

See docs.google.com [14] for full raw data

We have tested the wifi cards and antennas listed above. As expected, the internal wifi cards (Intel WiFi Link 5100 AGN & EDIMAX EW-7811Un) performed very poorly, detecting only 6 and 4 wifi networks respectively. The Alfa AWUS036H performed better than the specs would predict, detecting 13 wifi networks with a 2 or 5 dBi antenna. The major outlier was the Rosewill RNX-N2LX, detecting a massive 15 wifi networks with a 5 dBi antenna.

19. Project Yagimoto: General

Yagimoto, named for the intended antenna type (Yagi) + moto(r), is a robot that automatically aims antennas at an access point. Yagimoto uses a tripod-mounted yagi antenna and two servos to aim the antenna toward the optimal wifi signal strength.

20. Project Yagimoto: Hardware

Yagimoto's hardware is very simplistic. It uses a heavily modified tripod. We removed the head of a Vanguard VS-82 tabletop tripod (discussed above), and replaced it with a metal plate from our kit. We then attached a servo to it, facing upward, and another servo to that one facing sideways. Lastly, we attached a metal beam from our kit to the horizontal servo, with our Yagi antenna's metal plate screwed into that metal beam. This allows the antenna to tilt up, down, left, and right by moving the two servos.



21. Project Yagimoto: Software - PC Side

We wrote Yagimoto's PC side using only preexisting programs and bash scripting. Of course, this limits Yagimoto to Linux only. We chose Linux because it is easier to access a list of wifi networks on Linux than on other operating systems. The original Yagimoto design used iwlist (source: linux.die.net [14]) to retrieve a list of available networks. Then, the program greped (source: gnu.org [16]) the list from iwlist into the signal strength for the specified network. Finally, Yagimoto served that signal strength via netcat (source: http://netcat.sourceforge.net [17]) for the CBC to access. Yagimoto's PC side repeated these steps infinitely to update the signal strength as the antenna moves. Unfortunately, iwlist was very slow, giving us a new reading about every 16 sec. We later replaced iwlist with Kismet (source: kismetwireless.net [18]) for obtaining signal strength. This resulted in a 5-fold increase in response time to about 3 sec. You must run Yagimoto's PC side as root. We used Ubuntu 12.04 (source ubuntu.com [19]) for all testing of Yagimoto's PC side, although almost any modern Linux distribution should work. We recommend Linux kernel 3.0 or newer for proper driver support.

22. Project Yagimoto: Software - CBC Side - Initial Setup

When you first run Yagimoto, it will set the servos to the default position (change *ServoInitPosX* & *ServoInitPosY* to change the default position with the provided code). Then, Yagimoto takes a signal reading, turns right 10 degrees, takes a another signal reading, turns left 20 degrees, and takes yet another signal reading. Yagimoto then uses these first few signal readings as the initial values for the main process (see below) to determine which way to turn the antenna. Yagimoto will repeat this process for the Y-axis once the X-axis is centered.

23. Project Yagimoto: Software - CBC Side - Main

Yagimoto's CBC side is very complex. Yagimoto receives the signal from the PC side via netcat. It then adjusts the position of the antenna based on the following flow chart (magnify the PDF if the text is too small):



Yagimoto does these steps with 10-degree increments, and 5-degree increments for both the X and Y axes. Yagimoto will immediately stop scanning if the past 3 signal readings are above -50 dBm because that would be an adequate signal strength.

24. Project Yagimoto: Manual Mode

Another feature we implemented was a manual mode in which you can stop Yagimoto, aim the antenna by hand, and then have Yagimoto continue the centering from there. This is useful if you already know the approximate location of the wifi network (e.g. aim it at the lobby of the hotel at which you are staying). To do this with the provided code, hold down the A button during the scanning process. Then, use the CBC's arrow keys to move the antenna in the specified direction. Press B to exit manual mode. The code checks for the A button before every movement.

25. Protecting Your Wifi Networks

Some people leave their wifi network open to share bandwidth with others. Because of this, many non-malicious people will assume that if you leave your wifi network unencrypted, you are fine with them having some free internet. If you do not want people (malicious or non-malicious) using your wifi, there are some measures you can implement to protect against them.

- 1. Encrypt your network with WPA2. WEP is very insecure and can be broken in minutes.
- 2. Use a password unaffiliated with the users of the network. Do NOT use your name, phone number, birthday, address, etc as your password.

Most users will avoid your network if it is encrypted, even with WEP. However, relying on being safe from "most users" is generally poor security practice, which is why we recommend the above measures instead of simply using WEP if you do not want neighbors using your internet access.

26. Protecting Yourself on Untrusted Networks

If you are on a public network (e.g. at a hotel), be careful. Malicious users can log everything you do, including your passwords. Using an extension such as HTTPS Everywhere (source: eff.org [20]) will protect you from most password thieves. In addition, it is a very bad idea to do online banking, or anything else risky, on a public wifi network.

27. Conclusion

We have produced a very viable system for connecting to wifi networks at long range, but we could optimize it further. Removing the computer from the system is something we are looking at for Yagimoto 2.0, perhaps based on KIPR's next robotics controller. We are also looking into connecting two Yagimotos to one computer to provide a backup connection in case one disconnects. If you ever want to find us, we are on the Botball Community regularly. You can also find the full, un-redacted version of this paper there with entire sections not seen anywhere else on the Botball Community.

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